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Patterns and Causes of Species Richness: A General Simulation Model for Macroecology

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For Review Only

Gotelli *et al.*A GSM For Macroecology
Ecology Letters (I & P)**Patterns and Causes of Species Richness:
A General Simulation Model for Macroecology**

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92 ABSTRACT

93 Understanding the causes of spatial variation in species richness is a major research focus
94 of biogeography and macroecology. Gridded environmental data and species richness
95 maps have been used in increasingly sophisticated curve-fitting analyses, but these
96 methods have not brought us much closer to a mechanistic understanding of the patterns.
97 During the past two decades, macroecologists have successfully addressed technical
98 problems posed by spatial autocorrelation, intercorrelation of predictor variables, and
99 non-linearity. However, curve-fitting approaches are problematic because most
100 theoretical models in macroecology do not make quantitative predictions, and they do not
101 incorporate interactions among multiple forces.

102
103 As an alternative, we propose a mechanistic modeling approach. We describe computer
104 simulation models of the stochastic origin, spread, and extinction of species' geographic
105 ranges in and environmentally heterogeneous, gridded domain and describe progress to
106 date regarding their implementation. The output from such a general simulation model
107 (GSM) would, at a minimum, consist of the simulated distribution of species ranges on a
108 map, yielding the predicted number of species in each grid cell of the domain. In contrast
109 to curve-fitting analysis, simulation modeling explicitly incorporates the processes
110 believed to be affecting the geographic ranges of species and generates a number of
111 quantitative predictions that can be compared to empirical patterns. We describe three of
112 the "control knobs" for a GSM that specify simple rules for dispersal, evolutionary
113 origins, and environmental gradients. Binary combinations of different knob settings
114 correspond to eight distinct simulation models, five of which are already represented in

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the literature of macroecology.

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117 The output from such a GSM will include the predicted species richness per grid cell, the

118 range size frequency distribution, the simulated phylogeny, and simulated geographic

119 ranges of the component species, all of which can be compared to empirical patterns.

120 Challenges to the development of the GSM include the measurement of goodness of fit

121 between observed data and model predictions, as well as the estimation, optimization,

122 and interpretation of the model parameters. The simulation approach offers new insights

123 into the origin and maintenance of species richness patterns, and may provide a common

124 framework for investigating the effects of contemporary climate, evolutionary history,

125 and geometric constraints on global biodiversity gradients. With further development, the

126 GSM has the potential to provide a conceptual bridge between macroecology and

127 historical biogeography.

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130 KEYWORDS. Species richness, macroecology, biogeography, geographic range, mid-

131 domain effect, mechanistic simulation modeling

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132 INTRODUCTION

133 If a Cartesian grid is superimposed on the earth's surface, counts of species richness
134 within each grid cell will not be uniform or distributed randomly in space. For many taxa,
135 species richness is correlated with geometric and geographic properties of the grid cells—
136 their surface area, isolation, latitude, longitude, and elevation or depth. These properties
137 are themselves often correlated with grid-cell measures of contemporary climate, such as
138 average temperature and annual precipitation. Understanding the mechanistic basis of
139 these patterns remains the holy grail of modern biogeography and macroecology (Willig
140 *et al.* 2003). This “richness problem” has been studied for over two centuries (Forster
141 1778; Wallace 1878; Rosenzweig 1995), and over 100 ecological and evolutionary
142 hypotheses have been proposed to resolve it (Rohde 1992; Palmer 1994). Because of the
143 large spatial grain and extent of these patterns, experimental approaches are rarely
144 possible, and we must infer mechanisms from modeling and statistical analyses
145 (Diamond 1986). Correlative procedures for analyzing macroecological data have
146 become increasingly sophisticated and powerful, but we are not necessarily getting much
147 closer to a definitive understanding (Rohde 1992; Willig *et al.* 2003).

148

149 In this paper, we briefly review the “curve-fitting” approach that has dominated
150 contemporary analyses of species richness data. We argue that more mechanistic
151 approaches that model the origin and spread of species geographic ranges in a
152 heterogeneous landscape offer a potentially more powerful framework for investigating
153 species richness and associated macroecological patterns. This general simulation model
154 (GSM) is a relatively simple form of pattern-oriented modeling (Grimm *et al.* 2005), in

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155 which a bottom-up model is used to predict system-level properties. In this paper, we
156 describe a GSM for macroecology: a general stochastic modeling framework for
157 simulating processes such as speciation, dispersal, and extinction in a heterogeneous
158 landscape.

160 THREE GRIDDED DATA LAYERS

161 Three kinds of data layers are typically used to analyze spatial patterns of species
162 richness: (1) a gridded map of a biogeographic domain, such as a continent or bioclimatic
163 region; (2) species occurrence records within each grid cell of the domain; and (3) a set of
164 contemporary (or increasingly, historical or future) environmental variables measured for
165 each grid cell in the domain, such as average temperature, net primary productivity, or
166 topographic relief. These data layers are used in analyses of species richness patterns and
167 form the inputs to the GSM.

169 Although beyond the scope of this paper, we note that many potential sources of error are
170 associated with each data layer, and that the effect of these errors will probably vary with
171 the spatial scale of the analysis. Recent studies have begun to explore the effects of
172 measurement errors (e.g., Scott *et al.* 2002; Mathias *et al.* 2004; Guralnick & van Cleve
173 2005; Hurlbert & Jetz 2007). However, in most analyses, process and measurement error
174 are not distinguished, and they are pooled into a single error term. For now, we take the
175 same approach and assume that, for high-quality data sets analyzed at an appropriate
176 spatial scale, the underlying biogeographic signal of the data is not seriously distorted by

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177 inevitable uncertainty in the data layers. Explicit modeling of the processes that give rise
178 to sampling errors is a promising avenue for future research.
179
180 CURVE-FITTING ANALYSES OF SPECIES RICHNESS PATTERNS
181 How are the three kinds of data layers (gridded domain, species occurrences, and
182 environmental variables) typically analyzed? Until recently, the most common approach
183 has been to treat each grid cell as an independent sample, and then search for correlations
184 between species richness and climate variables within the domain. For example, a simple
185 linear regression of species richness of South American birds with net primary
186 productivity (Rahbek *et al.* 2007) accounts for 44% of the variation in species richness
187 among 1 x 1 degree grid cells (Figure 1). This curve-fitting approach, which typically
188 uses linear functions and log-transformed data, has characterized hundreds of published
189 analyses that invoke measures of contemporary climate as arguably causal mechanisms
190 of patterns in species richness. The strength of the mechanism is often inferred from the
191 goodness of fit (usually measured by r^2), and by the frequency of studies that show such
192 patterns. For example, Hawkins *et al.* (2003) concluded from a meta-analysis that 83 of
193 85 studies strongly supported some aspect of the water-energy hypothesis, because
194 species richness was significantly correlated with grid-cell measures of temperature or
195 precipitation. In single-factor regression analyses, climatic variables explained on
196 average 60% of the variation in species richness in continental areas (Hawkins *et al.*,
197 2003).

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199 LIMITATIONS OF CURVE FITTING

200 The technical challenges of spatial autocorrelation (Rangel *et al.* 2006), inter-correlated
201 predictor variables (MacNally 2002), non-linear responses of species richness to
202 environmental variables (Mittelbach *et al.* 2001), and effects of spatial scale (Nogues-
203 Bravo *et al.* 2008) have defined much of the research program in macroecology for the
204 past decade. Curve-fitting analyses have successfully identified repeated patterns of
205 correlation between species richness and climatic variables. However, this extensive
206 curve-fitting activity has not led to satisfying explanations for the underlying causes of
207 species richness gradients (Currie *et al.* 2004).

208
209 As noted by Currie *et al.* (1999), the core problem is that most hypotheses to account for
210 large-scale variation in species richness are specified so vaguely that they don't predict
211 anything more precisely than a qualitative latitude-richness correlation (which served to
212 motivate many of the hypotheses in the first place) or a simple correlation of species
213 richness with measures of contemporary climate (which does not lead to unique
214 predictions for different hypotheses). Notable exceptions include the species energy
215 model (Wright 1983), the mid-domain effect (Colwell & Lees 2000), and metabolic
216 theory (Allen *et al.* 2002), all of which have recently been used to derive quantitative
217 predictions of species richness patterns and to test those predictions with empirical data
218 (Currie *et al.* 2004, Jetz & Rahbek 2001, Hawkins *et al.* 2007). A second problem is that
219 both contemporary and historical factors influencing species richness are likely to interact
220 in complex ways. We lack a body of theory to explain how these mechanisms will
221 interact. Although causal modeling (Shipley 2009) is a potential approach to this

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problem, it has rarely been used in macroecology. The more common approach of using simple or multiple regression analysis is not an effective way of dealing with multicollinearity (Burnham & Anderson 2002). A final problem with curve-fitting is that the response variable in the statistical model—species richness per grid cell—is the total number of species whose geographic ranges overlap each grid cell in the domain. A mechanistic understanding of species richness patterns should be based on modeling the actual species ranges themselves, rather than the aggregate variable of their summed overlap in each grid cell. The GSM directly addresses all three of these problems: it generates quantitative predictions of species richness per grid cell, incorporates multiple interacting processes, and models species ranges directly.

BIOCLIMATIC DISTRIBUTION MODELING STRATEGIES

Bioclimatic species distribution models (Pearson & Dawson 2003; Elith *et al.* 2006) use occurrence data to infer the environmental niche limits of a species, employing a variety of model-fitting tools (Thuiller 2003; Latimer *et al.* 2006) and validation criteria (Araújo *et al.* 2005). Although bioclimatic species distribution models are essentially a form of sophisticated curve fitting, they are becoming more mechanistic (Thuiller *et al.* 2008). Recent models have incorporated processes such as dispersal and extinction (Iverson 2004, De Marco *et al.* 2008), and have been coupled with stochastic population models (Keith *et al.* 2008). As species distribution models become more mechanistic, they converge in strategy with the modeling approach we advocate here.

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244 Why not, then, simply apply bioclimatic species distribution models to each species in an
245 assemblage, and then sum the predictions for each grid cell to derive expected species
246 richness (McPherson & Jetz 2007; Fitzpatrick *et al.* 2008)? The primary reason we do not
247 pursue this approach is that it requires estimating potentially hundreds of parameters as
248 each species distribution is fitted, optimized, and “trimmed” using historical and
249 ecological considerations. In contrast, we prefer a modeling strategy in which a set of
250 similar, but not identical, species are modeled with a much smaller number of parameters
251 (perhaps less than a dozen). An intermediate strategy for characterizing variation among
252 species would be a “random effects” model in which species differences are characterized
253 by a probability distribution for each model parameter, or a model in which species are
254 assigned to different functional groups, each with a different set of specified parameter
255 values.

256

257 Of course, these deliberate simplifications can introduce other problems. For example,
258 estimating dispersal with a single dispersal kernel for all species might give very different
259 results from a model in which the dispersal kernel for each species was estimated
260 separately. Colwell *et al.* (2009) have shown that, even in a homogeneous domain with a
261 simple Poisson dispersal kernel, there is a strong interaction between dispersal distance μ
262 and geographic range size in their effects on species richness per grid cell. At small and
263 intermediate, but identical, range sizes, a simple spreading dye model produces complex
264 species richness patterns that do not resemble a simple mid-domain effect (Colwell *et al.*
265 2009). These effects of range size would be more accurately represented with separate

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parameters for each species in an assemblage than with a model that treats all species identically.

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However, we can point to several examples of important models in ecology, including equilibrium theory (MacArthur & Wilson 1967), neutral theory (Hubbell 2001), and the metabolic theory of ecology (Brown *et al.* 2004), that assume species are “similar” and are fitted with common parameters. These models have been surprisingly successful at explaining many patterns in large multi-species assemblages. Indeed, the underlying premise of macroecology is that much of the variation in species assemblages is driven by only a small number of deterministic forces that can be described with simple stochastic equations (Brown 1995, Maurer 1999).

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Finally, suppose the bioclimatic species distribution modeling perspective is correct, and the distribution of each species in nature must be represented by a unique model with parameters that are distinct from those of other species in the assemblage. If this were true, the resulting pattern of species richness might be expected to be complex and highly variable, but would not necessarily correlate very well with environmental or geographic variables because the predicted set of optimum conditions would be different for each species. In fact, species richness of many taxonomic groups correlates very strongly with latitude, longitude, elevation, and a suite of associated environmental variables (Rosenzweig 1995). For the same reason that macroecologists have been successful in using curve-fitting models to describe species richness as a function of water and energy

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variables (Hawkins *et al.* 2003), we believe there is merit in pursuing a modeling approach that does not focus on idiosyncratic differences among species.

MECHANISTIC SIMULATION MODELS FOR SPECIES RICHNESS PATTERNS

To overcome the limitations of the curve-fitting approach, and to avoid the unwieldy strategy of predicting species richness by stacking species distribution models for individual species, we propose a third alternative: mechanistic models that simulate speciation, dispersal, and extinction of species in a heterogeneous landscape (represented as a gridded domain). Simulation models are characteristically probabilistic and stochastic, so that multiple iterations of the same model can be used to empirically estimate the expected number of species (and its variance) in each grid cell of the domain, under the conditions of the model. A comprehensive, general simulation model must be flexible enough to incorporate and adjust major driving mechanisms of contemporary, past, or future climates, evolutionary and historical forces, and geometric constraints. These mechanisms can be accommodated in a single GSM, potentially providing a common framework for investigating hypotheses about the relative influence on species richness of geometric constraints, climatic factors, and historical processes.

However, the GSM poses some new challenges. It forces an explicit consideration of the precise rules that govern the origin of species and the expansion of their geographic ranges in a bounded domain, and it requires an estimate of the parameters that control these processes. Because the GSM approach predicts species richness patterns as they arise from the overlap of species ranges, the mechanisms by which range dynamics occur

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311 must be explicitly defined and coded as computer algorithms that operate with a specific
312 time step and in a logical sequence.

313

314 The algorithms in the GSM represent a set of rules that govern the location, probability,
315 and mechanism of speciation, the inheritance of niche characteristics by each new species
316 from its immediate ancestor, and the ability of each species to disperse to new grid cells
317 and successfully colonize them based on their environmental characteristics. The model
318 could be run for a given number of evolutionary time steps, until a particular number of
319 species ranges are simulated, or until a balance between speciation and extinction is
320 achieved, leading to a stationary distribution of species richness.

321 CONTROL KNOBS OF THE GSM

322 Each algorithm or procedure in the GSM can be thought of as controlled by a rotary
323 knob, switch, or dipswitch (Rosenzweig & Abramsky 1997). The setting of the control
324 knob specifies the value of either a continuous parameter (e.g., like a water faucet) or a
325 discrete multi-state parameter (e.g., like an automobile headlight switch). Even a
326 relatively simple model might have a dozen such control knobs. For purposes of
327 discussion, it is useful to think of one of the settings on each knob as a “ground” or “null”
328 state (the “off” position on the water faucet or the headlight switch) that represents a
329 parsimonious or unconstrained condition for the process. As an illustration, we consider
330 just three of the control knobs in a GSM and their possible settings: dispersal distance,
331 evolutionary origins, and environmental gradients.

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Dispersal Limitation. This control knob specifies limits on the distance, in grid-cell units, that each species is able to disperse in a single time step of the model, thereby potentially colonizing a grid cell that it does not already occupy. The “ground state” for this control knob would be dispersal within the domain that is unconstrained by distance, so that a species could potentially reach any grid cell in the domain in a single dispersal event. Many models in macroecology fit this scenario (Brown 1995); they describe assemblages for which species richness is ultimately determined by energetic constraints and other factors operating within a grid cell, unconstrained by the ability of species to reach those grid cells (Brown *et al.* 2004). At the other extreme, initial models of the mid-domain effect (Colwell & Lees 2000) invoked strict range cohesion, so that species geographic ranges could spread only through contiguous, unoccupied grid cells. This constraint may reflect many biologically realistic processes that limit range expansion at smaller spatial scales, including environmental heterogeneity (Connolly 2005), strong dispersal limitation (Swenson & Howard 2005), source-sink dynamics (Curnutt *et al.* 1996), and metapopulation structure (Keitt *et al.* 2001). Between the extremes of unconstrained dispersal and strict range cohesion, the dispersal limitation control knob could be set to allow for dispersal across intervening grid cells (e.g., Rangel & Diniz-Filho 2005b, Dunn *et al.* 2006, Colwell *et al.* 2009). Patch dynamics models reflect cases in which the intervening habitat is unsuitable for colonization (Connolly 2005).

The shorter this dispersal distance, the more closely the model will resemble the range cohesion model, and the longer the dispersal distance, the more closely the model will resemble unconstrained, spatially homogeneous dispersal. The longer the dispersal

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356 distance, the more holes or discontinuities will be generated in each species' geographic
357 range. Alternatively, patchy distributions could also arise in models with contiguous
358 range expansion if local extinction is allowed to occur within occupied grid cells (Bokma
359 *et al.* 2001; Rangel & Diniz-Filho 2005b; Davies *et al.* 2005; Connolly 2009). We have
360 had good success with a simple dispersal model in which dispersal distances follow a
361 Poisson distribution with a common dispersal parameter μ for all species in the
362 assemblage (Gotelli *et al.* 2007, Colwell *et al.* 2009). Modeling dispersal in this way
363 allows for occasional long-distance dispersal events, but requires the investigator to make
364 decisions about which occupied grid cells are more likely to serve as dispersal sources.
365 Does dispersal depend on the environmental conditions in the source and/or the target
366 grid cell, or does it depend on the location of the source cell within the currently occupied
367 range (edge versus interior grid cells)? What is the fate of propagules targeted to disperse
368 beyond the edge of the domain? Are these propagules "lost" or can they "stop short" to
369 colonize unoccupied cells at the edge of the domain? If the grid cells in the domain are
370 fairly large, a model of contiguous dispersal into adjacent cells may be more appropriate.
371 In this case, the algorithm is similar to cellular automata, with rules specified for
372 spreading into the adjacent 4 or 8 cells (von Neumann or Moore neighborhoods,
373 respectively). In preliminary trials (Gotelli, unpublished data), both methods give similar
374 results, although the 8-cell Moore neighborhood is more efficient and leads to less porous
375 species distributions.

376

377 Evolutionary origins. This control knob sets the number of independent evolutionary
378 origins for modeling the biota. The ground state of this control knob defines n

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independent evolutionary origins for a biota of n species. The origin of each species is a unique event, and evolutionary history (i.e. the position of the geographic range of the ancestor species) does not have an influence on the resulting pattern. Moreover, niche inheritance and niche conservatism (Losos 2008) are not explicit in this model: the niche of each species is independent of the niche of all other species. Most existing range-based models of species richness (Jetz & Rahbek 2001; Grytnes 2003; Connolly 2005; Storch *et al.* 2006; Rahbek *et al.* 2007) treat the origin of each species as an independent event.

At the other extreme, a single evolutionary origin might initiate an entire clade that is distributed within a domain. In this class of models, each new species originates only within (or adjacent to) the geographic range of its ancestor. Evolutionary history potentially influences the pattern of species richness, and the model generates not only the expected species richness per grid cell, but also a phylogeny, both of which could be compared to empirical data. Bokma *et al.* (2001), Rangel & Diniz-Filho 2005a, Rangel *et al.* (2007), and Roy & Goldberg (2007) provide examples of such evolutionary models that include a single ancestral taxon that gives rise to a set of n extant taxa within a domain. As our understanding of the evolutionary relationships and biogeographic history of real organisms improves, it will become possible to set empirical values for the n independent origins parameter. For example, Pennington & Dick (2004) estimated that up to 20% of tree taxa in a sample of an Ecuadorean forest were members of clades descended from long-distance immigrants from Africa.

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401 The algorithmic details will need to address the geographic mode of speciation. If
402 speciation is sympatric or from long-distance dispersal (peripheral isolates), then the
403 algorithm must specify the cell of origin and the dispersal kernel. If speciation is
404 allopatric, then the algorithm must specify how existing geographic ranges are
405 fragmented and whether the probability of fragmentation depends on measured
406 environmental variables. Rangel *et al.* (2007) successfully used a stochastic sine-wave
407 function to simulate climate change and fragment ranges in an evolutionary model. These
408 authors also used two simple, stochastic variables to control the “heritability” of the
409 environmental niche from ancestor to descendant taxon—one for the niche center in
410 niche space and the other for niche breadth. The niche center parameter encompassed the
411 extremes between perfect niche conservatism (the daughter taxon retains the
412 environmental niche center of the parent taxon) to rapid evolutionary adaptation (the
413 niche center of the daughter taxon evolves to match the mean environmental conditions
414 of the parental range fragment from which the daughter originates). The niche breadth
415 parameter controls the range of conditions tolerated around the niche center.
416
417 Environmental gradients. This control knob determines whether speciation, dispersal, or
418 extinction are equiprobable among grid cells or depend on particular environmental
419 variables. Although most analyses and discussion of environmental variables focus on
420 contemporary climate, new reconstructions of paleoclimates (Breuer *et al.* 2007, Salzman
421 *et al.* 2008) and paleo-richness (FAUNMAP 2009) may provide data for realistic
422 historical models that can be analyzed with the GSM. Several control knobs may be
423 necessary because the environmental factors that affect speciation might not be the same

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ones that determine dispersal or extinction. For terrestrial biotas, temperature and precipitation are two variables that are important correlates of large-scale patterns of species richness, and therefore are likely candidate variables for the cell-by-cell weighting of dispersal and net speciation rates. The water-energy model provides an emerging framework that may eventually yield functional forms for water and energy variables derived from first principles of physiology and physical constraints (O’Brien, 2006). For now, however, these models are either conceptual only (Vetaas, 2006; McCain 2007), or derived from regression parameters fitted to particular data sets (O’Brien, 1998). Regardless of the details of the algorithms that determine the way in which climate affects the size and location of geographic ranges, the ground state of this control knob is a model in which all grid cells are equiprobable within a pre-defined geographic domain and zero elsewhere.

MODEL VARIATIONS

Thus far, our simplified GSM has three control knobs (dispersal distance [DD], evolutionary origins [EO], and environmental gradients [EG]) that specify some key algorithms for simulating geographic ranges of species. If we consider each control knob in its dichotomous off-on settings (where “off” represents the ground state), we generate a set of eight qualitatively different kinds of simulation models (Table 1). Five of these models correspond well with recently published analyses and large-scale simulations.

The simplest model, with all three control knobs in the ground state [0-0-0; no dispersal limitation, *n*-evolutionary origins, equiprobable environments], would yield a Poisson distribution of species richness per grid cell because each species occurrence is placed

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447 randomly, equiprobably, and independently throughout the domain. This model
448 corresponds to the statistical null hypothesis that is tested in many regression and curve-
449 fitting analyses. Levins' (1969) original formulation of a single-species metapopulation
450 model also matches this category, as colonization occurs among patches in a
451 homogeneous environment with no dispersal limitations. However, the Levins (1969)
452 model is dynamic, as it includes continuous local extinction and recolonization, and it is
453 not spatially explicit.
454
455 Imposing range cohesion and allowing each species to originate independently, in an
456 equiprobable environment [1-0-0] describes the algorithm for the spreading dye model
457 (Jetz & Rahbek 2001), in which each species originates in a randomly chosen grid cell,
458 and then its range expands randomly and equiprobably into contiguous unoccupied grid
459 cells until its specified range is filled. The spreading dye model is the simplest two-
460 dimensional simulation model of the mid-domain effect (Colwell & Lees 2000). The
461 analytical models of Grytnes (2003) and Connolly (2005) also fall in this category,
462 although they do not constrain the frequency distribution of range sizes to match the
463 empirical data. This category also includes models with partial dispersal limitation in a
464 patchy environment (Connolly 2005).
465
466 Including only the constraint of evolutionary origins [0-1-0, a single geographical origin
467 for all species] in an equiprobable, but bounded environment probably will not generate
468 any geographic gradients in species richness, because all cells in the domain are
469 equivalent and are equally accessible to colonists. However, because the origin of new

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species is no longer independent of the placement of previous species, this class of models could generate important deviations from a Poisson distribution of species richness and variance per grid cell.

A model with no dispersal limitation and multiple origins but with environmental gradients that affect origination, extinction, or migration [0-0-1] is consistent with many hypotheses that invoke contemporary climatic or environmental effects (e.g., temperature, precipitation, productivity, harshness, or environmental heterogeneity) as the primary determinants of species richness patterns. These scenarios, described as “range scatter” models by Rahbek *et al.* (2007), assume that historical and evolutionary forces are relatively unimportant in determining patterns of contemporary species richness. Species are potentially able to reach all suitable grid cells within the domain, so that local species richness is controlled by some aspects of energy or other contemporary abiotic variables. Predictions of models in this category would be similar to simple regression-based analyses of species richness, which implicitly assume that species richness within a grid cell does not depend on its location within the domain and is determined only by those environmental variables included in the regression model and a stochastic error term (e.g. Hawkins *et al.* 2003).

Imposing a dispersal constraint on a model with environmental gradients and multiple origins [1-0-1] produces a hybrid model that combines climatic and mid-domain effects, leading to a spreading dye model in a heterogeneous environment (Storch *et al.* 2006; Rahbek *et al.* 2007). For the South American avifauna, these “range cohesion” models

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493 did a better job of predicting species richness for wide-ranging species than did either
494 simple spreading dye models [1-0-0] or range scatter models [0-0-1] (Rahbek *et al.*
495 2007).
496
497 Models that specify a single evolutionary origin and dispersal limitation in an
498 equiprobable environment [1-1-0] capture the spirit of the neutral model (Hubbell 2001),
499 but differ from classic neutral models in specifying a bounded domain. At large
500 biogeographic scales, with strong dispersal limitation, these models can generate mid-
501 domain peaks of species that are qualitatively similar to the predictions of the spreading
502 dye and other two-dimensional mid-domain effect models (Rangel & Diniz-Filho 2005b).
503 Models that characterize speciation, colonization, and extinction dynamics at the patch
504 scale (rather than as individual births and deaths) also belong in this category
505 (evolutionary origins models of Bokma *et al.* 2001; Davies *et al.* 2005; analytical patch
506 occupancy models of Connolly 2009).
507
508 Models that include effects of environmental gradients and a single evolutionary origin
509 but no dispersal constraint [0-1-1] have not been explored. Depending on the details of
510 the speciation mechanism that is modeled, the lack of a dispersal constraint may or may
511 not erase historical effects that arise during speciation.
512
513 The most complex combination in the GSM proposed here includes dispersal limitation, a
514 single evolutionary origin, and effects of environmental gradients [1-1-1]. Rangel &
515 Diniz-Filho (2005a) pioneered models in this class (in one and two dimensions), with a

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single, bounded, environmental gradient or geographical mosaic; a single evolutionary origin; and simple (peripatric) speciation and extinction rules. They showed that the resulting pattern of species richness is a balance between gradient strength and geometric constraints. Rangel *et al.*'s (2007) recent simulation of avian biogeography incorporates all of these effects on a complex map (South America), and incorporates many other "control knobs" that specify rules for environmental fluctuation, range fragmentation and extinction, and the inheritance of the environmental niche characteristics from ancestor to descendant species.

Although each of the studies discussed here involves much more detail, specification of just three of the control knobs in the GSM effectively encompasses and classifies most published analytical and simulation models in macroecology.

ESTIMATING, OPTIMIZING, AND INTERPRETING MODEL PARAMETERS

Even a relatively simple simulation model can potentially contain many parameters. It is unlikely that all of these can be estimated independently with empirical data (Ricklefs 2003), so values of such parameters will have to be chosen on the basis of biological insight, expert opinion, or parsimony. The parameters can then be adjusted or optimized to generate the best possible fit between the model output and empirical data. Parameter optimization for a GSM may be especially computationally intensive because a large number of model simulations will have to be run for each parameter combination to estimate the model's predicted values of response variables. Moreover, applying standard algorithms for finding best-fit parameter values (e.g., simplex, gradient, or simulated

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annealing approaches; Kelly 1999) is also problematic because goodness-of-fit surfaces for these stochastic models will not necessarily be smooth, so simplex and gradient algorithms may not converge on the optimal parameter sets. Genetic programming or reverse engineering algorithms (Bongard & Lipson 2007) may be needed to efficiently locate optimal (or near optimal) parameter combinations.

This strategy of adjusting and optimizing the parameters would produce a single synthetic model that incorporates several interacting mechanisms. Such a model would probably reflect the intuition of many macroecologists about the multiple factors that affect species richness (Harrison & Cornell 2007). However, such a model is likely to be unnecessarily complex. An alternative approach is to begin “turning off the control knobs” of Table 1, and trying to construct simpler models to account for variation in species richness. Rather than optimizing parameters to generate a single complex model, this approach uses the GSM to generate a suite of simple (null) models that can be viewed as alternative hypotheses. If there are n binary control knobs, there are 2^n parameter combinations or qualitatively distinct models. This number may become prohibitively large for a realistic GSM, but it may not be necessary to test all model combinations to address the interactions of a few key mechanisms.

Finally, a comparative approach could be used for *a priori* comparisons of taxonomic groups that differ in dispersal ability or other features, or comparisons of a single taxonomic group among different biogeographic domains that differ in geological

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histories. In this way, the GSM can be used to explore complex narratives and hypotheses in historical biogeography (see FUTURE CHALLENGES).

DEFINING THE RESPONSE VARIABLE

Explaining the observed pattern of species richness per grid cell is the principal objective for building the GSM. In theory, different models can be assessed or ranked solely on the basis of their ability to account for variation in species richness. However, cases may arise in which two different models predict a similar pattern of species richness. For example, an evolutionary model that posits higher speciation rates closer to the tropics (Rohde, 1992, Allen & Gillooly 2006, Allen *et al.* 2002, 2006), a niche conservatism model with tropical origins (e.g. Rangel *et al.* 2007), and an energetic model that posits more species where there is higher temperature or more energy available (Currie *et al.* 2004) would all predict a positive correlation between species richness and temperature.

How can we decide between competing models in such cases? Grimm *et al.* (2005) advocate the analysis of multiple response variables in assessing the output of complex simulation models. One of the great benefits of using the GSM is that it can generate many secondary predicted patterns for analysis. The output from any single run of the GSM can be organized as a binary presence-absence matrix, in which columns are the grid cells, rows are species, and the matrix elements represent the presence (1) or absence (0) of a given species in a particular grid cell (Gotelli 2000). Traditional metrics derived from presence-absence matrices include the column sums (yielding the species richness per site, our primary response variable) and the row sums (resulting in the number of sites

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584 in which each species occurs). In this context, the row sums represent the predicted
585 range-size frequency distribution, which can be a possible secondary response variable
586 (Rangel *et al.* 2007).

587

588 Moving beyond the simple row and column sums, presence-absence matrices enable the
589 generation of additional response variables, including the “dispersion field” (Graves &
590 Rahbek 2005), which is the set of geographic range sizes of species occurring in a given
591 cell, and the “diversity field”, which is the set of richness values of cells within the range
592 of a given species (Arita *et al.* 2008). Patterns of dispersion and diversity fields may
593 assist in model discrimination and evaluation. Other potential response variables that
594 exploit the structure of the full matrix include the location of centers of endemism (Jetz *et*
595 *al.* 2004), the degree of nestedness of the species assemblage (Ulrich *et al.* 2009),
596 measures of beta diversity (Anderson *et al.* 2006, Jost 2007, Chao *et al.* 2008), and
597 patterns in the scaling of species richness, including the species-area relationship (Arita
598 & Rodriguez 2002; Lyons & Willig 2002).

599

600 An entirely different dimension can be added to all these metrics if rows (species) are
601 classified according to a phylogeny generated by the model itself, and the geographic
602 position of columns (grid cells) is explicitly included in the model. This enables the
603 analysis of response variables in spatial and temporal evolutionary contexts that might
604 allow a finer tuning of contrasting models. First, the shapes of the generated phylogenies
605 themselves can be compared with observed phylogenies using metrics such as tree
606 balance (e.g, Heard & Cox 2007) and the pattern of lineage-branching pattern through

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time (e.g., White *et al.* 2006; Alroy 2008; Phillimore & Price 2008). Second, the phylogenetic community structure (*sensu* Webb 2000) of taxa co-occurring in samples of spatially contiguous cells can be compared between observed and simulated cases. We expect high phylogenetic clustering at these biogeographic scales either when dispersal limitation is high and a spatial signature of speciation persists for a long time (Graham & Fine 2008), or when strong environmental gradients are combined with strong phylogenetic niche conservatism (Wiens & Graham 2005; Losos 2008). Third, specific phylogeographic patterns can be examined: e.g., how often in simulated cases do taxa within some spatially- or environmentally-defined region form a clade of the same size and shape as is seen in the observed phylogeographic distribution? A latitudinal gradient of species richness could thus be examined, shedding light on the many competing evolutionary hypotheses that have been proposed to explain the pattern (Wiens & Donoghue 2004; Jablonski *et al.* 2006, Mittelbach *et al.* 2007; Arita & Vázquez-Domínguez 2008; Jablonski 2008). Finally, if additional traits or attributes of species have been measured, there are numerous indices for describing the distribution of trait states among terminal taxa (e.g. Blomberg *et al.* 2003).

In combination with species richness per cell, all these secondary patterns facilitate discrimination among models. However, there are difficulties with this approach because not all of the response variables are produced by all of the models, and some models make use of the empirical distribution of some of the response variables. For example, the evolutionary model of n independent origins does not generate a phylogeny; conversely, many simple spreading dye models use the observed range-size frequency

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630 distribution to generate model predictions, so these variables could not used to evaluate
631 models. Indeed, it is arguable that formal model selection statistics should not be used for
632 any response variables when comparing, e.g., a model that uses the observed range size
633 frequency distribution and one that predicts the range size frequency distribution. -An
634 additional challenge is that models that optimize the fit to one of the response variables
635 (such as the number of species in each grid cell) may do so at the expense of others (such
636 as the range size frequency distribution). Although the GSM predicts species richness and
637 a number of other macroecological patterns, it is unclear how much weighting should be
638 given to secondary patterns for the purposes of assessing goodness-of-fit.

639

640 ASSESSING MODEL ADEQUACY AND COMPARING MODELS

641 For a GSM to be useful, we must be able to identify models that fit the observed data
642 well, to measure the adequacy of the fit for each model, and to rank competing models
643 against one another in terms of their predictive power. We focus here on modeling the
644 number of species in each grid cell, leaving aside other model predictions such as
645 phylogenetic patterns or range size frequency distributions.

646

647 A good model will have little or no bias, meaning that it will accurately predict observed
648 species richness in each grid cell. In the best case scenario, a good model will also be
649 precise, meaning that repeated stochastic trials of the same model will generate a small
650 variance in species richness in each grid cell. A classical measure of the adequacy of a
651 univariate estimator (U_N), calculated from a sample of size N to estimate a parameter θ , is

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the mean square error (*MSE*, e.g., Lehmann & Casella 1998), which includes the two components of bias and variance:

$$\begin{aligned} MSE &= E(U_N - \theta)^2 \\ &= [E(U_N) - \theta]^2 + \text{Var}(U_N) \\ &= [\text{Bias}(U_N)]^2 + \text{Var}(U_N) \end{aligned}$$

For our purposes, we shall ignore measurement error and treat the observed data as the “parameters” to be estimated by the model. Although more complex models may be more accurate, they may also generate greater variances among simulation trials and therefore be less precise. On the other hand, simpler models may be less variable among repeated simulation trials but may also be less accurate. The *MSE* therefore identifies models that strike a good balance between accuracy and parsimony.

The observed (empirical) data consist of a discrete count of the number of species within each of c grid cells on a two-dimensional surface, which we will denote by the vector \mathbf{O} , with elements O_1, O_2, \dots, O_c . Similarly, for a given model, a single stochastic outcome from a simulation of the model produces a species richness value within each of these grid cells. Let N be the number of simulations and S_{ik} be the value in the k^{th} grid cell ($k = 1, \dots, c$) for the i^{th} simulation ($i = 1, \dots, N$). An individual simulation surface will be denoted \mathbf{S}_i , which, like \mathbf{O} , is a vector of length c . For a large number of independent, stochastic simulations (say, $N = 10000$), the estimated expectation for the k^{th} grid cell is the average species richness:

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675

676

$$E_k \approx \frac{1}{N} \sum_{i=1}^N S_{ik}$$

677 We denote the vector of these expectations (also of length c) as \mathbf{E} .

678

679 Each vector of richness values can be represented as a point in c -dimensional space.680 From this perspective, the squared Euclidean distance from \mathbf{E} to \mathbf{O} , here denoted by681 $[D(\mathbf{O}, \mathbf{E})]^2$, measures bias because it is the sum of the squared deviations of the observed682 species richness (\mathbf{O}) from the expected species richness predicted by the model (\mathbf{E}):

683

684

$$\sum (\text{bias})^2 = [D(\mathbf{O}, \mathbf{E})]^2 = \sum_{k=1}^c (O_k - E_k)^2$$

685

686 Next, we can calculate a measure of the variability or (thinking geometrically) the

687 relative dispersion of the simulation points S_i in multivariate space (Anderson 2006). The688 Euclidean distance from simulation surface S_i to the average surface (or centroid) for all689 simulations from that model is $D(S_i, \mathbf{E})$. Dispersion is then calculated as the sum of690 squared distances from the individual simulation vectors to their centroid \mathbf{E} , divided by691 $(N - 1)$. This dispersion is equal to the sum (across all cells) of the variances in the

692 simulation values (calculated within each cell):

693

694

$$\sum (\text{var}) = \frac{1}{(N-1)} \sum_{i=1}^N [D(S_i, \mathbf{E})]^2$$

695

696 To compare the models directly with one another for their predictive capability, we can

697 use the sum of the MSEs, as follows:

698

699

$$\sum(\text{MSEs}) = [D(\mathbf{O}, \mathbf{E})]^2 + \frac{1}{(N-1)} \sum_{i=1}^N [D(S_i, \mathbf{E})]^2$$

700

701 Better models will have smaller values for this sum, which includes the components of

702 bias ($[D(\mathbf{O}, \mathbf{E})]^2$) and imprecision ($\frac{1}{(N-1)} \sum_{i=1}^N [D(S_i, \mathbf{E})]^2$). This index should not be used

703 to compare models if the parameters used in the models were themselves estimated from

704 the observed data. It can, however, be used to compare mechanistic models that

705 incorporate parameters that were derived independently of the observed data. Models can

706 be ranked on the basis of this index or other metrics that implicitly or explicitly measure

707 and trade off accuracy *versus* precision.

708

709 In addition to ranking a set of models according to their precision and low bias, it will

710 often be informative to assess the adequacy of a single model against the data. For testing

711 the goodness-of-fit (GOF) of a particular model based on count data such as species

712 richness, we suggest using the Kullback-Leibler (or K-L) distance (Kullback & Leibler

713 1951). The K-L distance ($K(\mathbf{O}, \mathbf{E})$) compares the observed (empirical) data \mathbf{O} with species

714 richness predicted by the model, \mathbf{E} :

715

$$K(\mathbf{O}, \mathbf{E}) = \log\left(\frac{n_E}{n_O}\right) + \frac{1}{n_O} \sum_{k=1}^c O_k \log\left(\frac{O_k}{E_k}\right)$$

717

718 where $n_E = \sum_k E_k$ and $n_O = \sum_k O_k$. For models in which the observed range size

719 frequency distribution is preserved, $n_E = n_O$, so the first term collapses to zero, and the K-

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720 L distance depends only on the difference between the observed and predicted species
721 richness for each grid cell. The K-L distance test differs by only a constant multiplier
722 from a likelihood ratio test of a given model *versus* a saturated model (see p. 336 in
723 Burnham & Anderson 2002).
724
725 The next step is to assess the distribution of the K-L distances under the null hypothesis
726 that the model is correct (i.e., its output accurately matches the empirical data). An
727 intuitive way to estimate this distribution is to simulate a large number of data sets (S_1 ,
728 $S_2, \dots, S_i, \dots, S_N$) that *do* conform exactly to the model's assumptions, and then calculate
729 the K-L distances associated with the simulated data sets (Tsay 1992; Waller 2003).
730 These K-L distances $K(S_i, E)$, $i = 1, 2, \dots, N$ form a parametric bootstrap distribution
731 (Efron & Tibshirani 1993; White 2002) that can be used directly for hypothesis testing.
732 The P -value is estimated directly as the proportion of simulated $K(S_i, E)$ distances that is
733 greater than or equal to $K(O, E)$. This empirical testing procedure assumes that
734 simulations are independent of one another, but (importantly) does not assume
735 independence among the cells within a given simulation, nor does it make any
736 assumption about the nature of the distribution of the K-L distances.
737
738 Analyses such as comparisons of MSE values and tests based on K-L distances will allow
739 investigators to quantify the accuracy and precision of different simulation models, to
740 rank competing models, and to perform GOF tests for individual models. These tests can
741 be performed on contemporary species distributions and environmental variables, but
742 they can also be adapted for evaluating changes in species richness through time. In

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743 addition, diagnostic tools and residual plots can be used to identify individual grid cells
744 or geographic regions in which a model's predictions consistently over or under-estimate
745 species richness.

746
747 FUTURE CHALLENGES

748 We have argued that stochastic simulation models of species occurrences provide a
749 powerful complement to traditional curve-fitting and more recent bioclimatic species
750 distribution modeling. However, the GSM is not a panacea. As with traditional curve
751 fitting and bioclimatic species distribution modeling, the results will be sensitive to the
752 spatial scale and taxonomic resolution of the data. Moreover, our ability to test historical
753 hypotheses will be limited by the availability of good phylogenies and (especially)
754 environmental data layers for historical climates. Nevertheless, simulation models hold
755 great promise for understanding the role of historical and contemporary forces in shaping
756 species richness patterns and for projecting species richness under climate change.

757
758 In closing, we note that the subdiscipline of historical biogeography (Morrone & Crisci
759 1995) also has tried to link patterns of species diversity to historical and evolutionary
760 processes through the mapping of contemporary diversity on phylogenies, areograms, and
761 vicariant events (Platnick & Nelson 1978; Rosen 1978; Nelson & Platnick 1980). Perhaps
762 the development of a detailed GSM will provide a conceptual bridge between
763 macroecology and historical biogeography (Brooks 1990; Cracraft 1994).

764
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Model	Dispersal Limitation	Evolutionary Origins	Environmental Gradients	References
Poisson Random Variable	0	0	0	Implicit null hypothesis in most curve-fitting analyses Levins (1969)
Spreading Dye	1	0	0	Jetz & Rahbek (2001), Grytnes (2003), Connolly (2005)
Evolutionary Origins	0	1	0	
Range Scatter	0	0	1	Implicit mechanistic model in most curve-fitting analyses (e.g., Hawkins <i>et al.</i> 2003)
Range Cohesion	1	0	1	Storch <i>et al.</i> (2006), Rahbek <i>et al.</i> (2007)
Neutral Model	1	1	0	Bokma <i>et al.</i> (2001), Rangel & Diniz-Filho (2005b), Davies <i>et al.</i> (2005) Connolly (2009)
Evolutionary Origins + Environmental Gradients	0	1	1	
Saturated Model	1	1	1	Bokma <i>et al.</i> (2001), Rangel and Diniz-Filho (2005a), Rangel <i>et al.</i> (2007), Roy & Goldberg (2007)

Table 1. Knob settings of a hypothetical GSM for simulating species richness patterns in a gridded domain. Knob settings of 0 represent a “ground state” for each knob. Dispersal Limitation: 0 = none, 1 = range cohesion or limited dispersal; Evolutionary Origins: 0 = n independent evolutionary origins for a fauna of n species, 1 = ($< n$) independent evolutionary origins, generally 1; Environmental Gradients: 0 = colonization and/or range expansion into all grid cells equiprobable, 1 = probabilistic colonization and/or range expansion into grid cells as a function of measured environmental variables.

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1078 Figure 1. Linear regression of species richness of South American endemic birds versus
1079 net primary productivity (NPP) ($r^2 = 0.44$, $p < 0.001$). Each point represents a
1080 single $1^\circ \times 1^\circ$ latitude-longitude grid cell ($n = 1676$). (Data from Rahbek *et al.*
1081 2007.)

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Figure 1.

